



Laboratory of

*Drives and Experimental
Automation
for Marine Systems*

Laboratory Manager:

Enrico Ravina, professor

Polytechnic School, DITEN, Naval Unit

Ph. : 0039-010-3532848; Cell.: 0039-3201804507; E-mail: enrico.ravina@unige.it

DREAMS Lab



Drives and Experimental Automation for Marine Systems

History

1990 : born the laboratory of Fluid Power Automation and Mechatronics

2011: the laboratory, which had gradually modified its activity with prevalent orientation to marine and naval field, begins *ADRINS* (Automation and *DR*ives for Naval Systems), at DITEN department

2012: born *DREAMS* Lab (*DR*ives and Experimental Automation for Marine Systems) with a new location at the Naval Unit of DITEN department. DREAMSs joints to MAT&ST research team

All the years the laboratory supported the activities of specific courses of Fluid Power Automation and Mechatronics

“Numbers” of the Laboratory:

26 : the years of the laboratory

'90 : activation of Fluid Power Automation module (second in Italy)

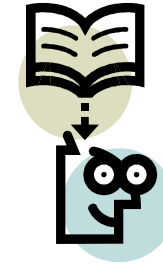
'94 : activation of Mechatronics module (first in Italy)

120 : number of publications in the last 10 years



Still its first activation the Laboratory is classified as relevant interest among laboratories by MIUR

Scientific activity: Proved by 295 publications on 26 years of activity (from 1990 to 2016).



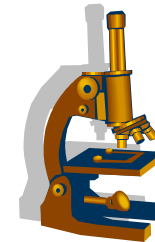
Didactic activity: Continuous support to

- Modules for Degrees and Masters
- Internships
- Degree and Master theses
- Phd



Prevalent research activities:

- Pneumatic and oil-hydraulic marine drives
- Marine and off-shore inspections
- Modelling and simulation of fluid power systems
- Diagnostics, monitoring and preventive maintenance of drives
- Characterization of fluidic innovative drives
- Experiments oriented to vibration and acoustics
- Applied mechatronics



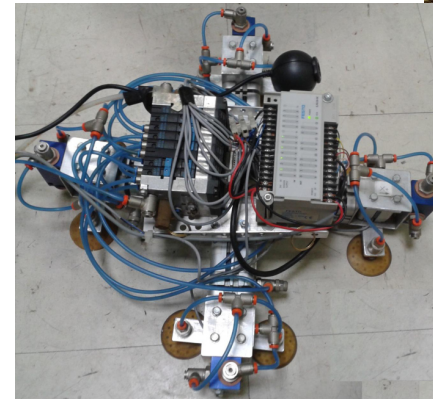
Automatized systems for marine inspections



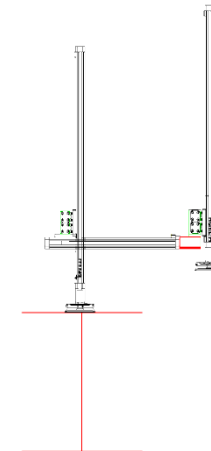
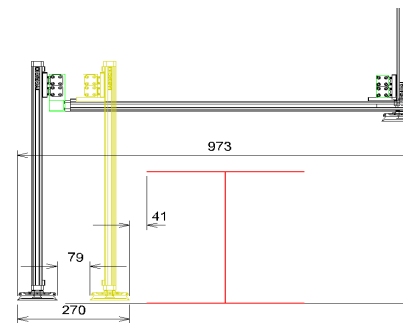
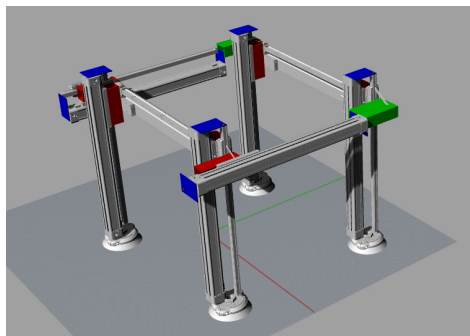
Worm robots for ducts inspection
driven by fluidic muscles



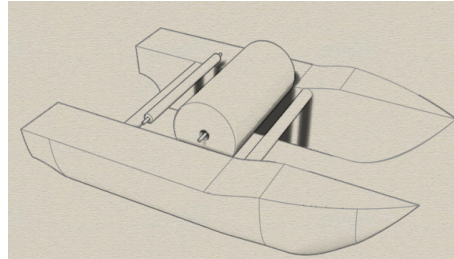
Hold inspection by means
of self-moving and
instrumented robotized
units



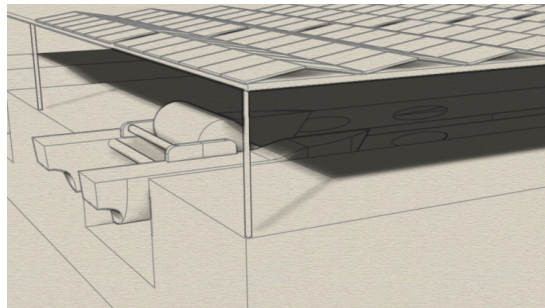
Bottom
inspection



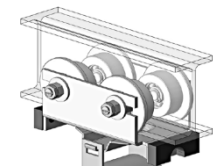
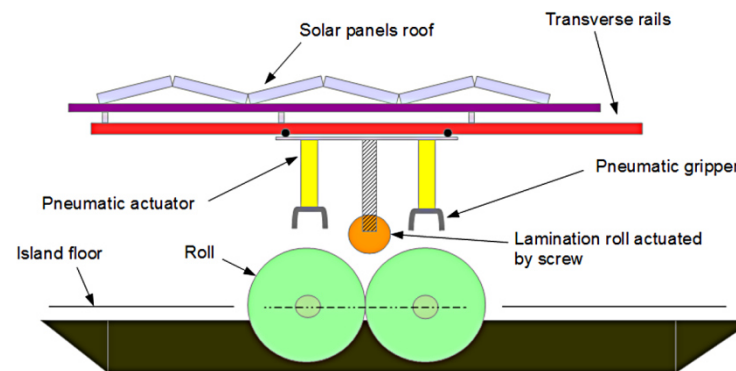
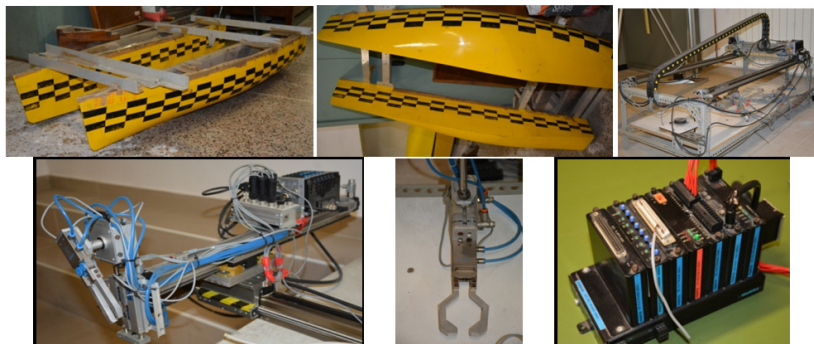
Sea-Cleaning Autonomous Units



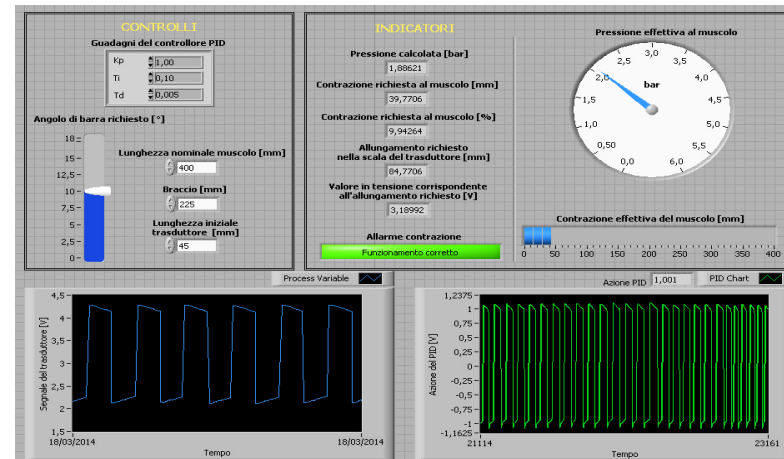
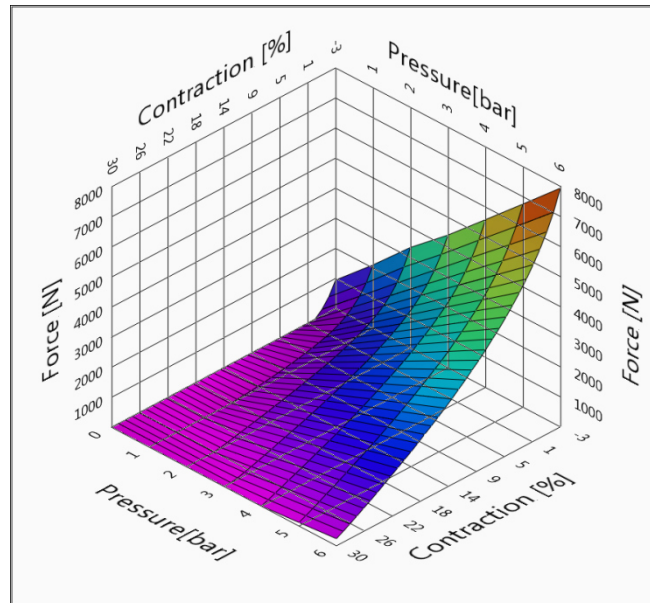
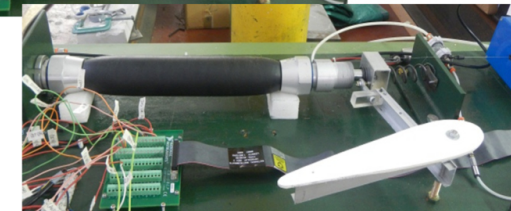
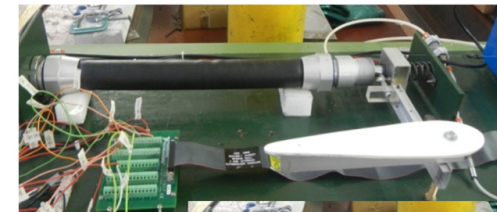
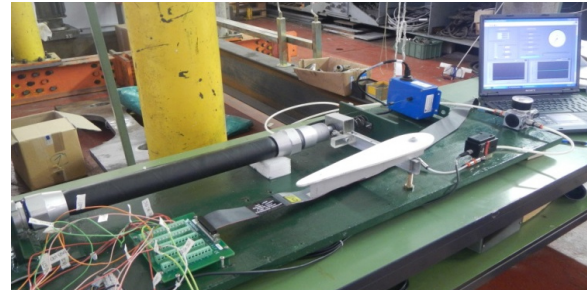
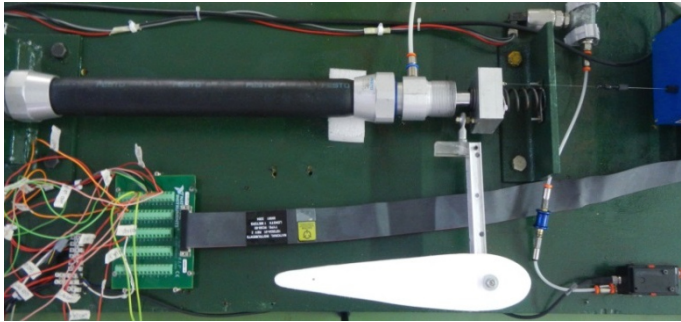
fleet of sea-cleaning autonomous units managed by waste-recovery island



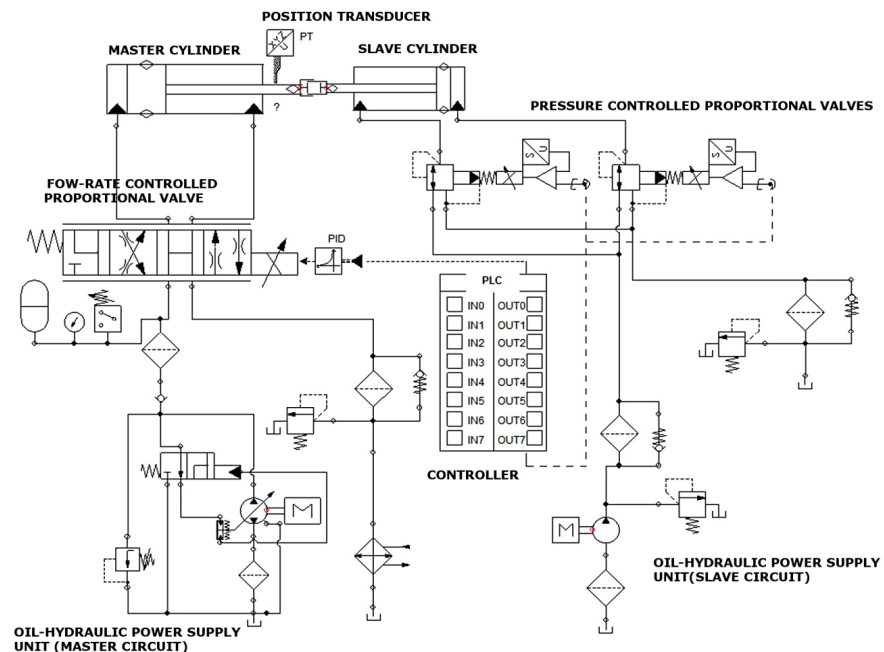
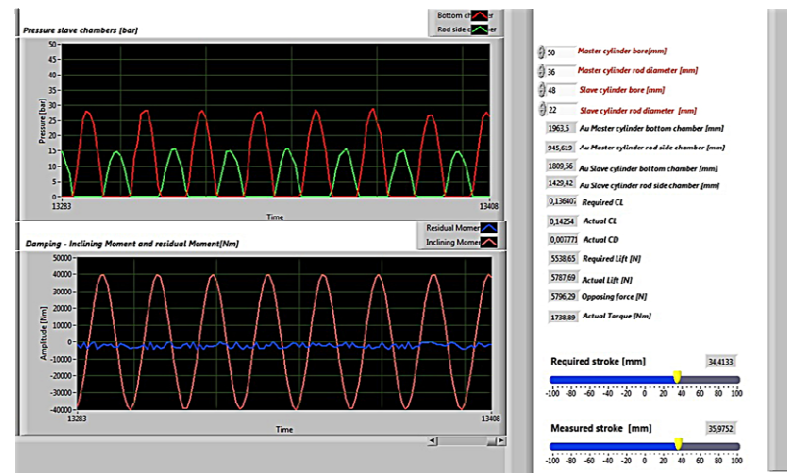
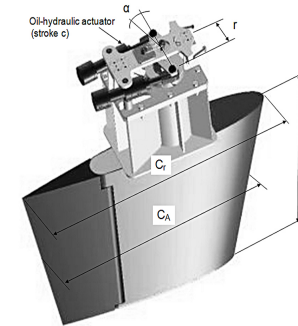
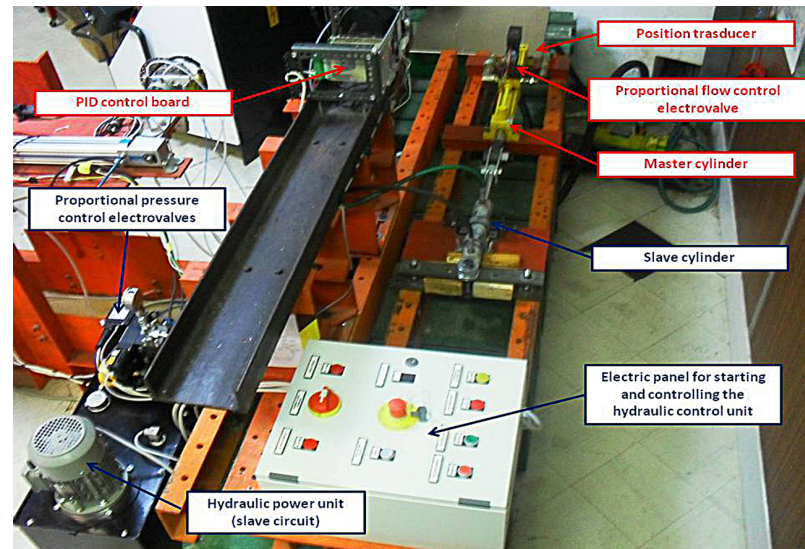
Implementation of preliminary designs of a non-conventional single unit of the “all-alike ships” fleet (BlackSheep) , assembling on board efficient wool recovery systems able to recover spilled oil from the sea surface.



Driving of rudders with fluidic muscles



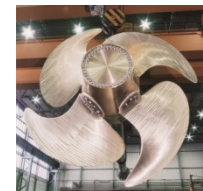
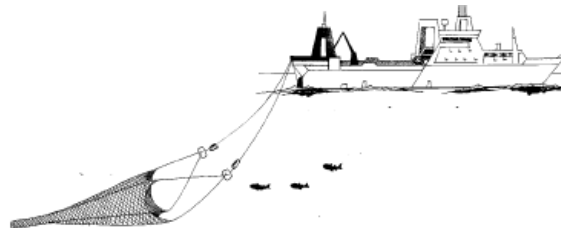
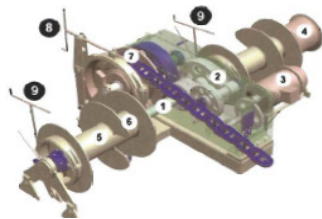
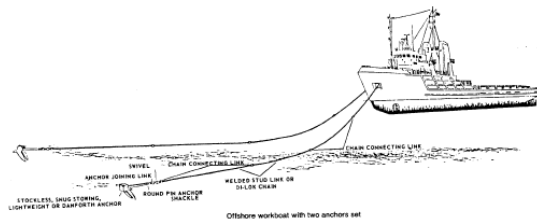
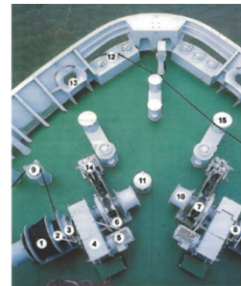
“Martronic” test bench for characterization of marine drives



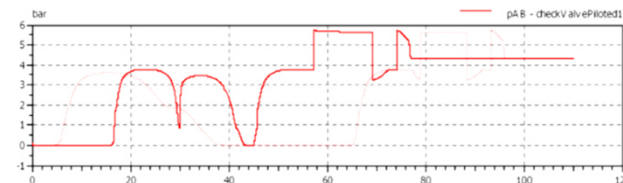
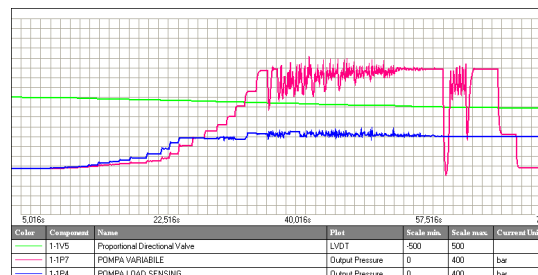
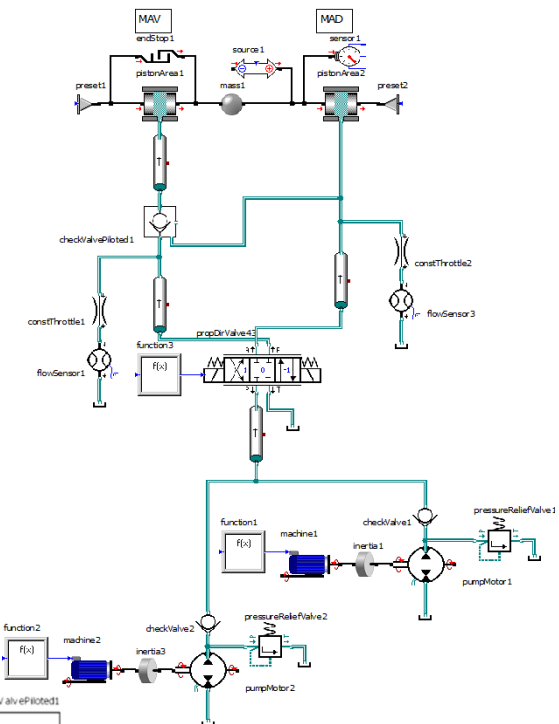
Automation of primary and secondary driving



Deck units: Analyses of load sensing driving



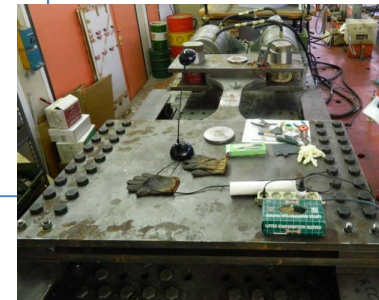
Trim of blades in adjustable pitch
propellers: modeling and dynamic simulation of components and circuit



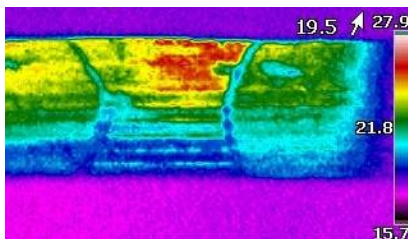
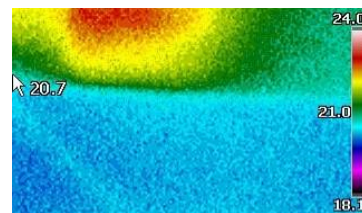
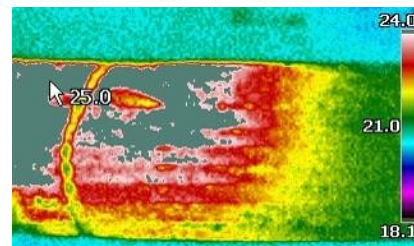
Monitoring, diagnostics and maintenance of structures, drives and marine systems



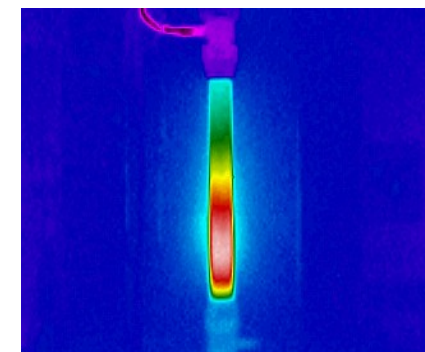
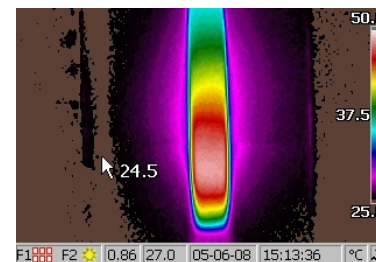
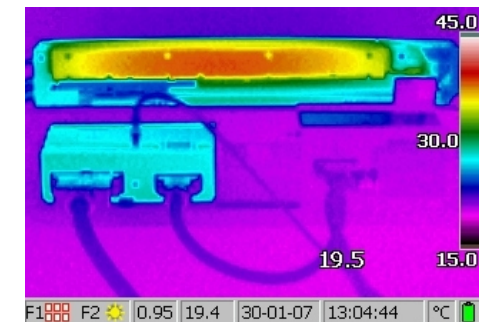
Driving of test bed for fatigue tests with servo-controlled oil-hydraulic units (in cooperation with MASTEL)



Thermo-graphic analyses of structures



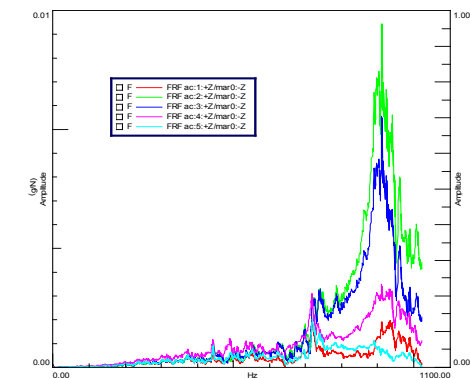
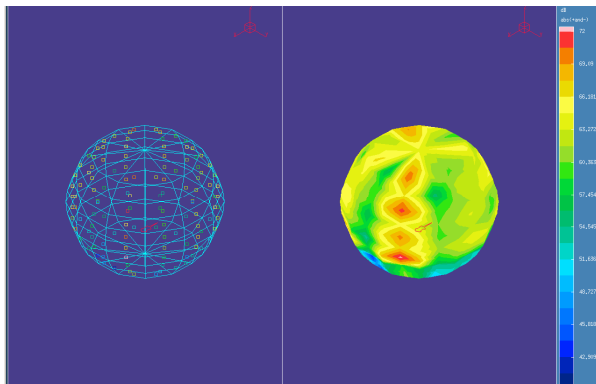
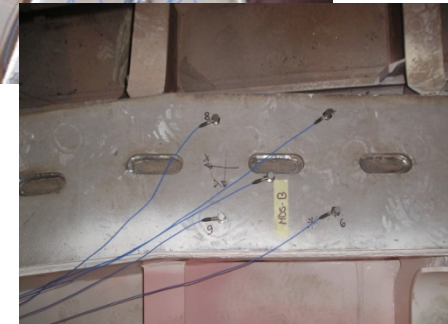
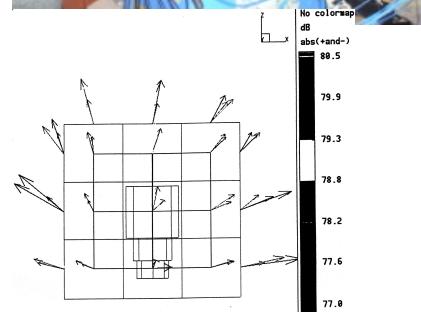
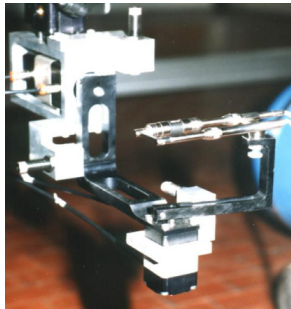
Diagnostics of the dynamic response of innovative actuators for naval drives



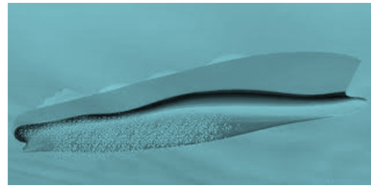
Vibratory and acoustic analyses in marine environments and on board components



- ❖ Dynamic analyses with 3D modeling
- ❖ Experimental modal analysis
- ❖ Acquisition and elaboration with portable units
- ❖ Detections with variable geometries microphones array
- ❖ Acoustic mapping
- ❖ Acoustic holography



Some activities under development



Experiments of air lubrication and air bubbling on hull models



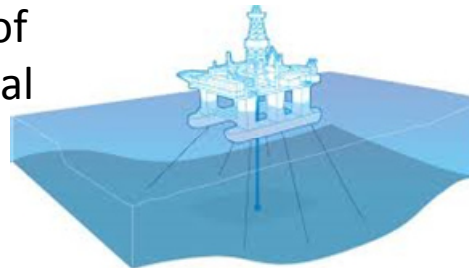
Desing of wavemaker with digital control for testing tank



Methodologies of diagnosis and maintenance of sub-systems on board (thrusters)



Simulation of platforms mooring in presence of extreme environmental conditions (squalls)



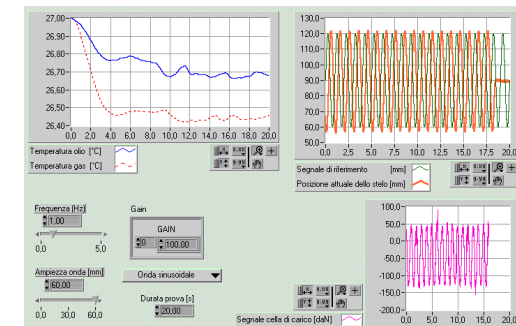
Structural dynamic interaction on supports of naval motors

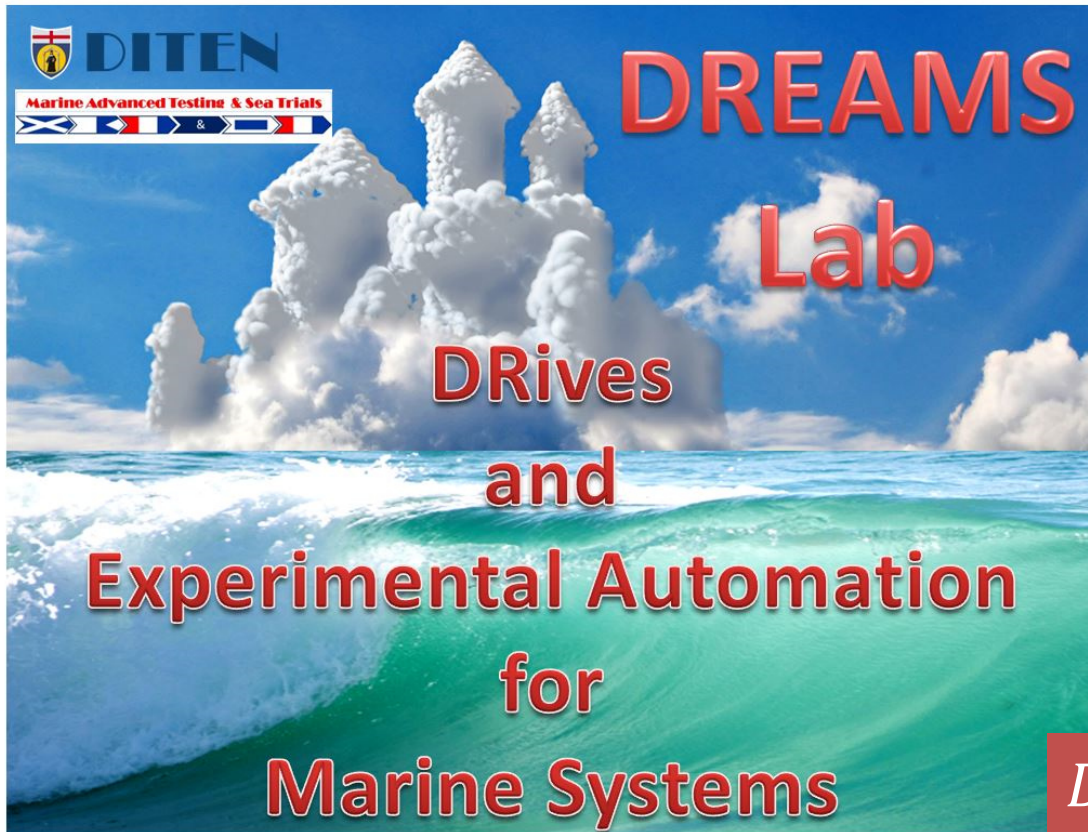


Detection of defects on marine structures by means vibro-acoustic techniques



Application of virtual instrumentation codes in monitoring and active control of unconventional test benches





Laboratory of

*Drives and Experimental
Automation
for Marine Systems*

Laboratory Manager:

Enrico Ravina, professor

Polytechnic School, DITEN

Ph. : 0039-010-3532848; Cell.: 0039-3201804507; E-mail: enrico.ravina@unige.it